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LectureNotesonLinearSystemTheory

A special class of linear time varying systems are linear time invariant systems, usually referred to by the acronym LTI LTI systems are described by state equations of the form $\dot{x}(t) = Ax(t) + Bu(t)$, $y(t) = Cx(t) + Du(t)$, where the matrices $A \in \mathbb{R}^{n \times n}$, $B \in \mathbb{R}^{n \times m}$, $C \in \mathbb{R}^{p \times n}$, and $D \in \mathbb{R}^{p \times m}$ are constant for all times $t \in \mathbb{R}^+$ LTI systems are

LINEAR STATE-SPACE CONTROL SYSTEMS

ear time-invariant systems Chapter 2 is concerned primarily with the state equation solution and connections with fundamental linear systems concepts along ...

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November 2, 2017 Time: 11:06am Chapter1tex 6 LECTURE 1 111 Terminology and Notation When the input signal u takes scalar values ($k = 1$) the system is called single-input (SI), otherwise it is called multiple-input (MI) When the output signal y takes scalar values ($m = 1$) the system is called single-output (SO), otherwise it is called multiple-output (MO) When there is ...

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